



EMERSON[™]
Industrial Automation

Unimotor

Product Data
055 to 190 Frames



0.72 Nm to 73.2 Nm




**CONTROL
TECHNIQUES**

www.controltechniques.com

Introducing the 055 to 190 frames.

Unimotor  is a range of brushless AC servo motors which support a winding to suit 200/240V or 400/480V nominal AC drives such as the Unidrive , Unidrive classic and Digitax ST range of drives. The range is available in six frame sizes 055:075:095:115:142 and 190mm, each frame size has a number of shaft diameter options and can offer various front flange mounting arrangements. The 190 frame motor has been increased in variants from 4 (A-D) to 8 (A-H). The design also conforms to the sealing standard IP65 (when mounted and connected).

Standard Features

- * Modular rotor design.
- * Rotor assembly balanced to ISO1940 (BS 6861) G 6.3.
- * Incremental encoder for high precision feedback.
- * PTC thermistors for thermal monitoring and overload protection.
- * IP65 standard; sealed against water spray and dust. (IP65 mating connectors must be used)
- * Vertical connectors for power and signal.
- * Low inertia is standard for fast acceleration.
- * UL and cUL recognised motors (075-190 frame motors only).  E21543
- * IEC mounting flange.
- * Shaft key as standard.

Optional Features

- * Parking brake.
- * High energy dissipation brake.
- * 90° fixed or 90° rotatable connectors.
- * A range of shaft diameters.
- * Optional IEC and NEMA flanges available.
- * High inertia.
- * Other Incremental encoder interfaces available.
- * Resolver feedback for rugged applications.
- * Sin/Cos encoder for high resolution and accuracy (single and multi-turn). Other interfaces available.
- * NEMA mounting available.
- * Plain shaft (non keyed).
- * Electronic name plating (Available on Sincos motors only). (075-190 frame motors only).
- * IP 54 rated motors (055 only).

Optional Products



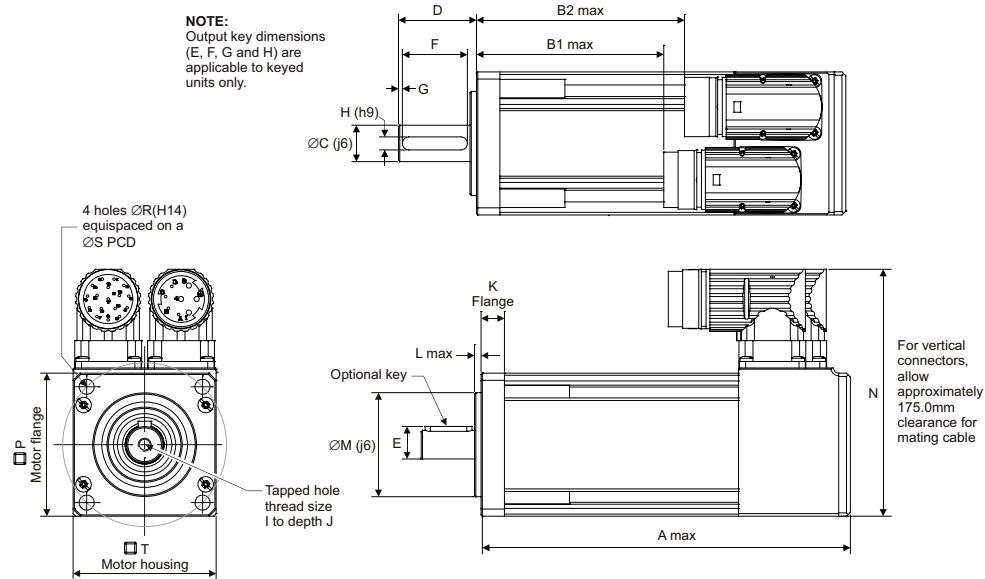
- * Cable assemblies for power and signal.
(Compliant to DESINA standard)



- * Gearbox options, high precision low backlash or general purpose, parallel shaft or right angle gearboxes available in various ratios.

* Where volumes have justified it, Control Techniques have designed a number of custom specific motors. Please contact your Drive Centre or Distributor for details.

Dimensions (mm) Frame size 055



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length			BRAKED Length			FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING
	A	B1	B2	A	B1	B2								
055A	118.0	48.0	56.0	158.0	88.0	96.0	9.0	2.5	40.0	96.0	55.0	5.8	63.0	55.0
055B	142.0	72.0	80.0	182.0	112.0	120.0								
055C	166.0	96.0	104.0	206.0	136.0	144.0								

Vertical connectors dimension (mm) Note: All dimensions shown are at maximum

	Unbraked Length		Braked Length		Power Connector	Signal Connector
	B1	B2	B1	B2	N	N
055A	75.0	83.0	115.0	123.0	104.0	93.0
055B	99.0	107.0	139.0	147.0	104.0	93.0
055C	123.0	131.0	163.0	173.0	104.0	93.0

Shaft Diameter (mm)

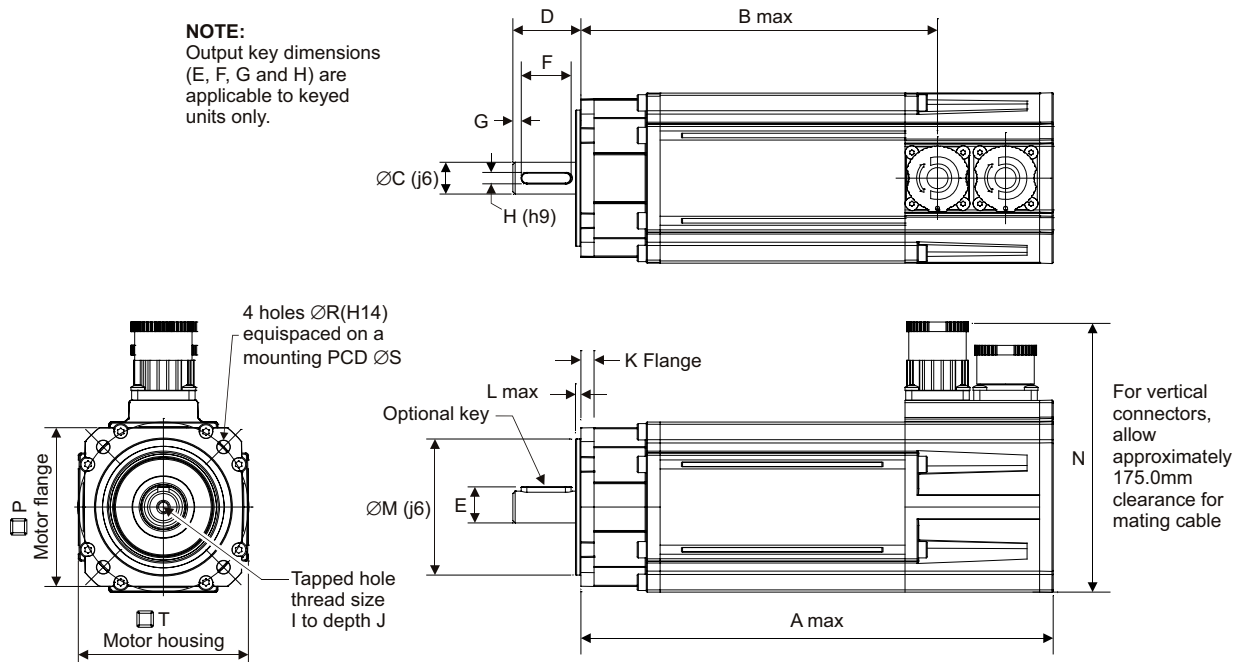
	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C (j6)	D	E	F	G	H (h9)	I	J
9.0	9.0	20.0	11.1	15.8	1.5	3.0	M4	12.5
11.0	11.0	23.0	13.4	18.8	1.2	4.0	M4	12.5
14.0	14.0	30.0	16.9	25.8	1.2	4.0	M5	15.0

Optional connector height (mm)

C type	96.0
V type	105.0

Dimensions (mm) Frame size 075

NOTE:
Output key dimensions
(E, F, G and H) are
applicable to keyed
units only.



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length		BRAKED Length		FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT VERTICAL	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING	MOUNTING BOLTS
	A	B	A	B									
075A	209.1	158.2	254.1	203.2	6.3	2.5	60.0	119.5	70.2	6.1	75.4	75.5	M5
075B	239.1	188.2	284.1	233.2									
075C	269.1	218.2	314.1	263.2									
075D	299.1	248.2	344.1	293.2									

Optional flange motor dimensions (mm)

	UNBRAKED LENGTH		BRAKED LENGTH	
	A	B	A	B
075A	193.5	142.6	238.5	187.6
075B	223.5	172.6	268.5	217.6
075C	253.5	202.6	298.5	247.6
075D	283.5	323.6	328.5	277.6

Optional flange dimensions (mm)

FIXING HOLE PCD	REGISTER DIAMETER	MOUNTING BOLTS
S	M	
66.7	60 +0/-0.05	M5
80.0	60	M5
85.0	70	M6

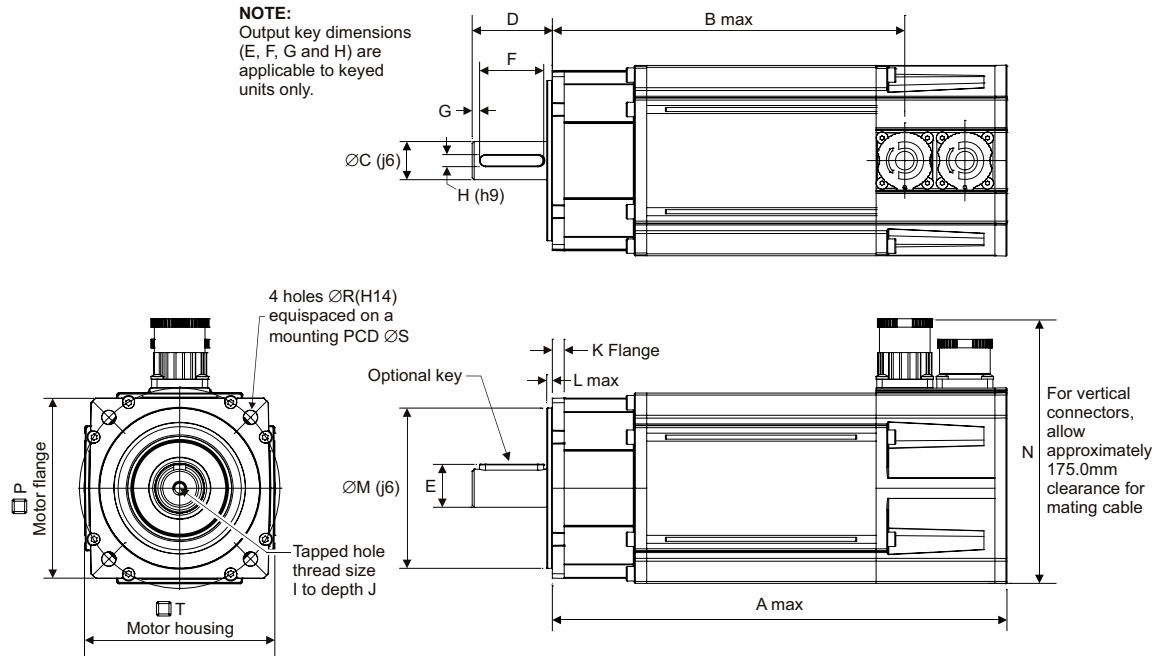
Optional connector height (mm)

CONNECTION TYPE	OVERALL HEIGHT
	N
A	119.0
B	127.0
C	127.0

Shaft Diameter (mm)

	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C (j6)	D	E	F	G	H (h9)	I	J
11.0 A Std	11	23.5	12.9	14.3	4.8	4.0	M4	11.4
14.0 B-D Std	14	30.5	16.3	22.3	4.8	5.0	M5	13.9
19.0 Max	19	40.5	21.8	32.3	4.8	6.0	M6	17.4

Dimensions (mm) Frame size 095



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length		BRAKED Length		FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT VERTICAL	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING	MOUNTING BOLTS
	A	B	A	B									
095A	227.8	176.9	272.8	221.9	6.4	2.9	80.0	132.5	90.2	7.0	100.4	95.6	M6
095B	257.8	206.9	302.8	251.9									
095C	287.8	236.9	332.8	281.9									
095D	317.8	266.9	362.8	311.9									
095E	347.8	296.9	392.8	341.9									

Optional flange motor dimensions (mm)

	UNBRAKED LENGTH		BRAKED LENGTH	
	A	B	A	B
095A	202.7	151.8	247.7	196.8
095B	232.7	181.8	277.7	226.8
095C	262.7	211.8	307.7	256.8
095D	292.7	241.8	337.7	286.8
095E	322.7	270.8	367.7	316.8

Optional flange dimensions (mm)

FIXING HOLE PCD	REGISTER DIAMETER	MOUNTING BOLTS
S	M	
98.83	73.025 +0/-0.05	M6
115.4	95 (j6)	M8

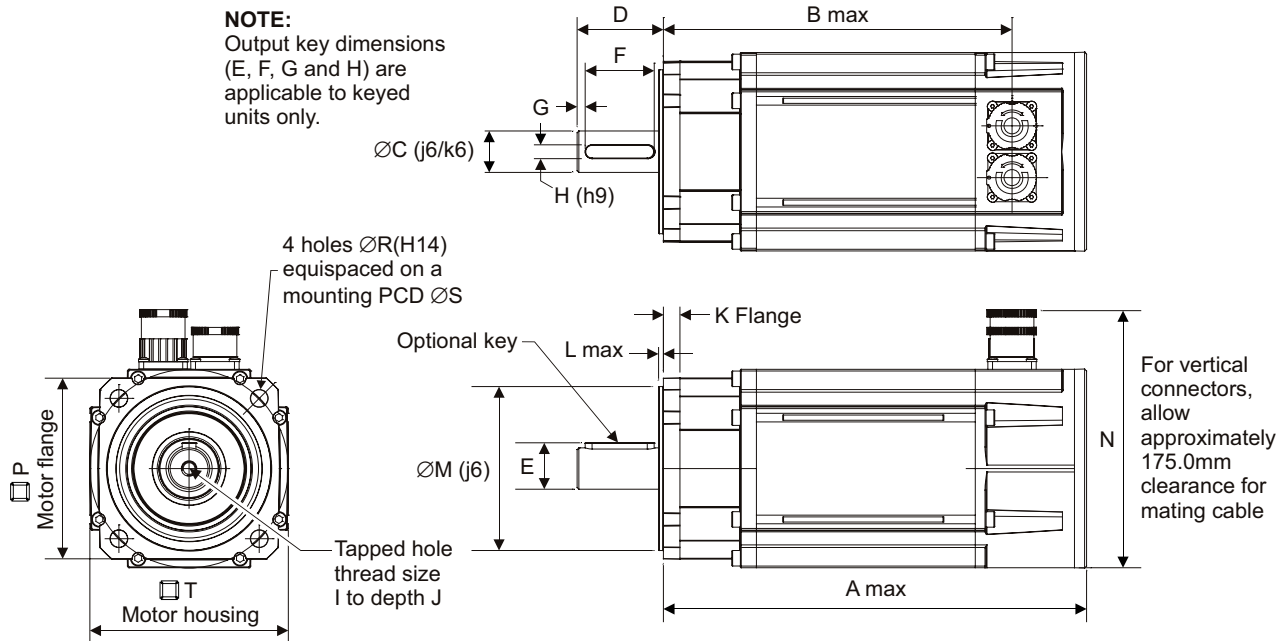
Optional connector height (mm)

CONNECTION TYPE	OVERALL HEIGHT
	N
A	132.0
B	140.0
C	140.0

Shaft Diameter (mm)

	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C (j6)	D	E	F	G	H (h9)	I	J
14.0 A Std	14	30.5	16.3	22.3	4.8	5.0	M5	13.9
19.0 B-E Std	19	40.5	22.8	32.3	4.7	6.0	M6	17.4
22.0 Max	22	50.5	24.8	40.3	5.8	6.0	M8	20.4

Dimensions (mm) Frame size 115



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length		BRAKED Length		FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT VERTICAL	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING	MOUNTING BOLTS
	A	B	A	B									
115A	246.1	203.0	291.1	248.0	10.1	2.9	95.0	150.0	105.2	10.0	115.4	115.6	M8
115B	276.1	233.0	321.1	278.0									
115C	306.1	263.0	351.1	308.0									
115D	336.1	293.0	381.1	338.0									
115E	366.1	323.0	411.1	368.0									

Optional flange motor dimensions (mm)

	UNBRAKED LENGTH		BRAKED LENGTH	
	A	B	A	B
115A	215.3	172.2	260.3	217.2
115B	245.3	202.2	290.3	247.2
115C	275.3	232.2	320.3	277.2
115D	305.3	262.2	350.3	307.2
115E	335.3	292.2	380.3	337.2

Optional flange dimensions (mm)

FIXING HOLE PCD	REGISTER DIAMETER	MOUNTING BOLTS
S	M	
126.1	110 +0/-0.05	M8
130.4	110 (j6)	M8
145.0	110 (h7)	M8

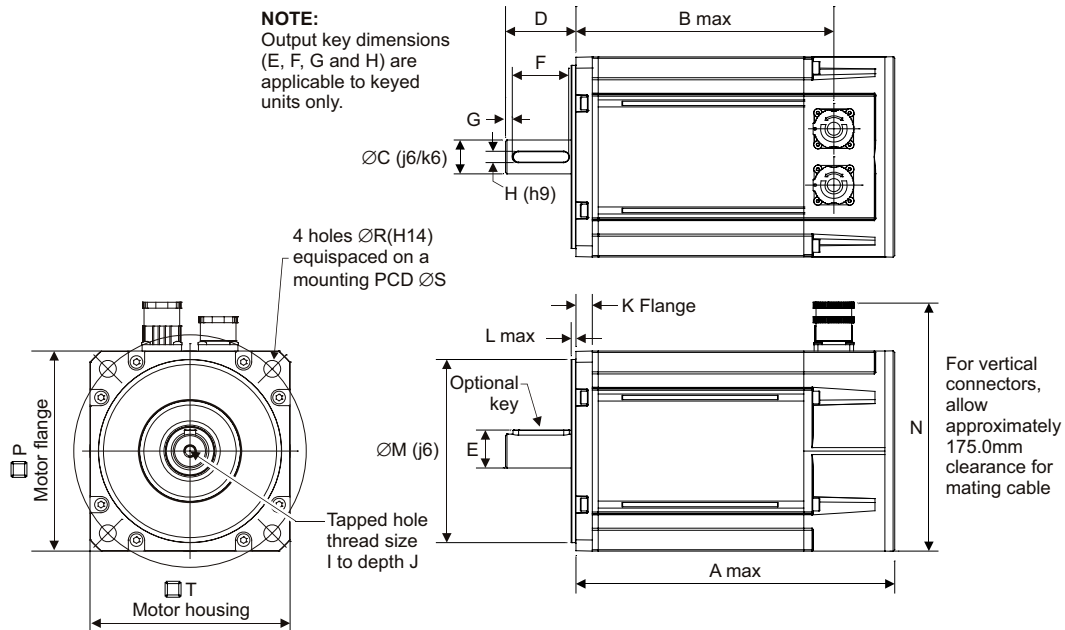
Optional connector height (mm)

CONNECTION TYPE	OVERALL HEIGHT
	N
A	149.5
B	157.5
C	157.5

Shaft Diameter (mm)

	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C	D	E	F	G	H (h9)	I	J
19.0 A-C std	19 (j6)	40.4	21.8	32.3	4.8	6.0	M6	17.4
22.0 Opt	22 (j6)	50.4	24.8	40.3	5.8	6.0	M8	20.4
24.0 D-E Std	24 (j6)	50.4	27.3	40.3	5.7	8.0	M8	20.4
28.0 Opt	28 (j6)	60.4	31.3	50.3	5.8	8.0	M10	23.4
32.0 Max	32 (k6)	80.4	35.3	70.3	5.8	10.0	M12	29.4

Dimensions (mm) Frame size 142



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length		BRAKED Length		FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT VERTICAL	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING	MOUNTING BOLTS
	A	B	A	B									
142A	227.1	184.0	272.1	229.0	12.1	3.6	130.0	177.0	142.2	12.0	165.4	142.7	M10
142B	257.1	214.0	302.1	259.0									
142C	287.1	244.0	332.1	289.0									
142D	317.1	274.0	362.1	319.0									
142E	347.1	304.0	392.1	349.0									

Optional flange motor dimensions (mm)

	UNBRAKED LENGTH		BRAKED LENGTH	
	A	B	A	B
142A	277.3	234.2	322.3	279.2
142B	307.3	264.2	352.3	309.2
142C	337.3	294.2	382.3	339.2
142D	367.3	324.2	412.3	369.2
142E	397.3	354.2	442.3	399.2

Optional flange dimensions (mm)

FIXING HOLE PCD	REGISTER DIAMETER	MOUNTING BOLTS
S	M	
149.23	114.3 +0/-0.076	M8

Optional connector height (mm)

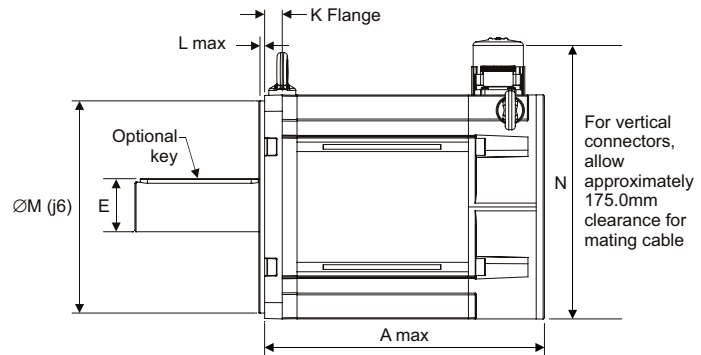
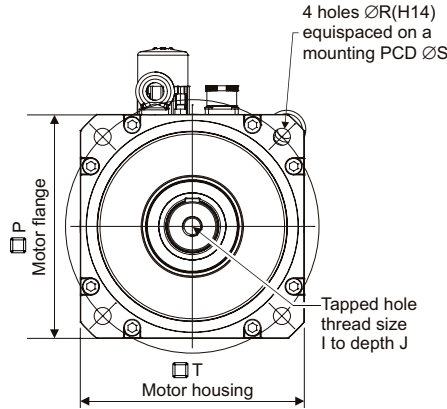
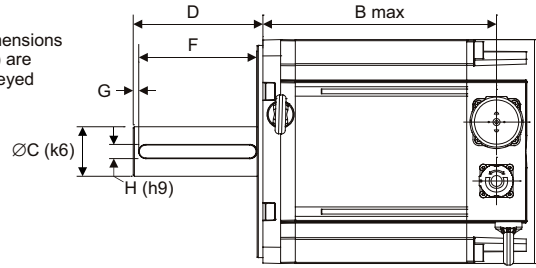
CONNECTION TYPE	OVERALL HEIGHT
	N
A	177.0
B	184.5
C	184.5

Shaft Diameter (mm)

	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C	D	E	F	G	H (h9)	I	J
22.0 Opt	22 (j6)	50.5	24.8	40.3	5.8	6.0	M8	20.4
24.0 A-E Std	24 (j6)	50.5	27.3	40.3	5.8	8.0	M8	20.4
28.0 Opt	28 (j6)	60.5	31.1	50.3	5.8	8.0	M10	23.4
32.0 Max	32 (k6)	80.5	35.3	70.3	5.8	10.0	M12	29.4

Dimensions (mm) Frame size 190

NOTE:
Output key dimensions
(E, F, G and H) are
applicable to keyed
units only.



Standard Motor Dimension (mm) Note: All dimensions shown are at maximum

	UNBRAKED Length		BRAKED Length		FLANGE THICKNESS	REGISTER LENGTH	REGISTER DIAMETER	OVERALL HEIGHT VERTICAL	FLANGE SQUARE	FIXING HOLE DIAMETER	FIXING HOLE PCD	MOTOR HOUSING	MOUNTING BOLTS
	A	B	A	B									
190A	238.3	199.2	319.1	280.0	15.5	4.0	180.0	233.0	190.2	14.5	215.0	191.5	M12
190B	265.2	226.1	346.1	307.0									
190C	292.2	253.1	373.0	333.9									
190D	319.1	280.0	400.0	360.9									
190E	346.1	307.0	426.9	387.8									
190F	373.0	333.9	453.9	414.8									
190G	400.0	360.9	480.8	441.7									
190H	426.9	387.8	507.8	468.7									

Optional connector height (mm)

CONNECTION TYPE	OVERALL HEIGHT
	N
A	246.0
B	253.5
C	253.5

Shaft Diameter (mm)

	SHAFT DIAMETER	SHAFT LENGTH	KEY HEIGHT	KEY LENGTH	KEY TO SHAFT END	KEY WIDTH	TAPPED HOLE THREAD SIZE	TAPPED HOLE DEPTH
	C (k6)	D	E	F	G	H (h9)	I	J
32.0 A-H Std	32	80.5	35.3	70.3	5.8	10.0	M12	29.4
38.0 Opt	38	80.5	41.3	70.3	5.8	10.0	M12	29.4
42.0 Max	42	110.5	45.4	100.3	5.8	12.0	M16	37.4

Motor Selection

Motor de-rating – Any adverse operating conditions require that the motor performance be de-rated. These conditions include; ambient temperature above 40°C, motor mounting position, drive switching frequency or the drive being oversized for the motor.

Ambient temperatures – The ambient temperature around the motor must be taken into account. For ambient temperatures above 40°C the torque must be de-rated using the following formula as a guideline. (Note: Only applies to 2000/3000rpm motors and assumes copper losses dominate)

$$\text{New de-rated torque} = \text{Specified torque} \times \sqrt{[1 - (\text{Ambient temperature} - 40) / (100)]}$$

For example with an ambient temperature of 76°C the new de-rated torque will be 0.8 x specified torque.

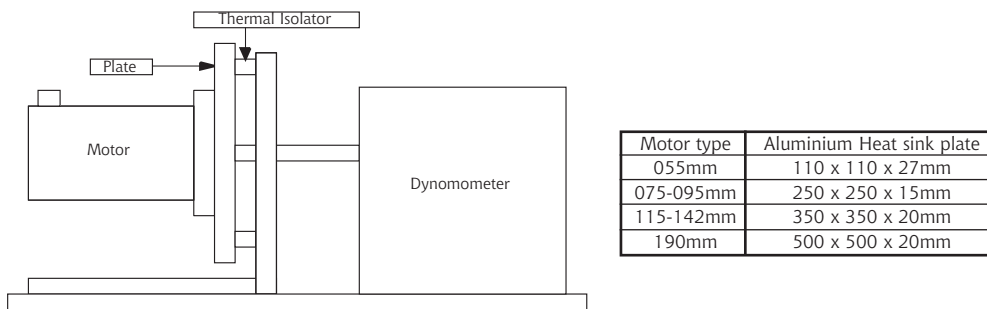
Mounting arrangements – The motor torque must be de rated if the motor mounting surface is heated from an external source, such as a gearbox. The motor is connected to a poor thermal conductor. The motor is mounted with the connectors on the side or vertical. The motor is in a confined space with restricted air flow.

Drive switching frequency – Most Unidrive SP and Digitax ST nominal current ratings are reduced for the higher switching frequencies see the appropriate drive manual for details.

See the table below for the motor de rate factors. These figures are for guidance only.
(Note: Only applies to motors up to 3000rpm and assumes copper losses dominate)

Motor de rate factors									
Switching frequency	Motor type/frame size								
	055	075	095	115		142		190	
	A-C	A-D	A-E	A-C	D-E	A-C	D-F	A-B	C-H
3kHz	0.84	0.93	0.88	0.89	0.84	0.87	0.81	0.98	N/A
4kHz	0.87	0.94	0.91	0.91	0.87	0.91	0.86	0.99	0.55
6kHz	0.90	0.95	0.93	0.93	0.90	0.94	0.89	0.99	0.77
8kHz	0.95	0.98	0.97	0.97	0.95	0.97	0.96	1	0.90
12/16kHz	1	1	1	1	1	1	1	1	1

Thermal test conditions – The performance data shown has been recorded under the following conditions. Ambient temperature 20°C, with the motor mounted on a thermally isolated aluminum plate as shown below.



Thermal protection – Thermistor protection (145°C) is built into the motor windings and gives an indication of serious overheating problems. The installer must connect the thermistor to the drive, failure to do so will invalidate the motor warranty in respect of a burnt out winding.

Environmental conditions – Any liquids or gases that may come into contact with the motor must be confirmed to ensure compliance with the correct international standards.

A		CA		A		100		190	
Output shaft	Feedback device			Inertia	PCD***		Shaft Diameter***		
A = Key (Std) B = Plain shaft X = Special	055 Frame only			055 Frame only	055 frame only				
	AR = Resolver			A = Standard	063 Std		09.0 Opt		
	CP = Incremental Encoder	4096 ppr			070 Opt		11.0 A-C Std		
	KP = Incremental Encoder	1024 ppr		075-190 Frame only			14.0 Max		
	EM = Inductive Sincos Multi turn			A = Standard	075 Std		11.0 A Std		
	FM = Inductive Sincos Single turn			B = High Inertia	080 Opt		14.0 B-D Std		
	MP = Incremental Encoder	2048 ppr			085 Opt		19.0 Max		
	TL = Optical Sincos Multi turn	SKM 36					095 frame only		
	UL = Optical Sincos Single turn	SKS 36				100 Std	14.0 A Std		
	XX = Special					098 Opt	19.0 B-E Std		
075-190 Frame only					115 Opt	22.0 Max			
EC = Inductive Sincos Multi turn	EQI 1331					115 frame only			
FC = Inductive Sincos Single turn	ECI 1319				115 Std	19.0 A-C Std			
EB = Optical Sincos Multi turn	EQN 1325				130 Opt	24.0 D-E Std			
FB = Optical Sincos Single turn	ECN 1313				145 Opt	32.0 Max			
AE = Resolver						142 frame only			
CA = Incremental Encoder	4096 ppr				165 Std	24.0 A-E Std			
MA = Incremental Encoder	2048 ppr				149 Opt	32.0 Max			
RA = Optical Sincos Multi turn	SRM 50					190 frame only			
SA = Optical Sincos Single turn	SRS 50				215 Std	32.0 A-H Std			
XX = Special						42.0 Max			

Unimotor For 3 Phase VPWM Drives 200-240Vrms

$\Delta t = 100^\circ\text{C}$ winding 40°C maximum ambient

All data subject to +/-10% tolerance

Motor Frame Size (mm)	055E2			075E2				095E2				
Frame Length	A	B	C	A	B	C	D	A	B	C	D	E
Continuous Stall Torque (Nm)	0.72	1.40	2.11	1.2	2.2	3.1	3.9	2.3	4.3	5.9	7.5	9.0
Standard (2) Peak Torque selection max (Nm)	2.75	5.50	8.25	3.6	6.6	9.3	11.7	6.9	12.9	17.7	22.5	27.0
High (P) Peak Torque selection max (Nm)	N/A	N/A	N/A	6	11	15.5	19.5	10.4	19.4	26.6	33.8	40.5
Standard Inertia (kgcm ²)	0.12	0.23	0.34	0.7	1.2	1.6	2.0	1.8	2.9	4.0	5.1	6.2
High Inertia (kgcm ²)				1.1	1.5	2.0	2.4	3.7	4.8	5.9	7.0	8.1
Winding Thermal Time Const. (sec)				81	74	94	100	172	168	183	221	228
Maximum Cogging (Nm)	0.03	0.05	0.07	0.02	0.03	0.04	0.05	0.03	0.06	0.08	0.10	0.13
Standard motor weight unbraked (kg)	1.20	1.50	1.80	3.60	4.40	5.20	6.00	5.10	6.30	7.50	8.70	9.90
Standard motor weight braked (kg)	1.60	1.90	2.20	4.10	4.90	5.70	6.50	5.70	6.90	8.70	9.30	10.50
Rated Speed 2000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 1.40 K_e (V/krpm) = 85.50								
Rated Torque (Nm)	C/D	C/D	C/D	1.1	2.1	3.0	3.8	2.2	4.0	5.5	6.9	8.2
Stall Current (A)				0.9	1.6	2.3	2.8	1.7	3.1	4.3	5.4	6.5
Rated Power (kW)				0.23	0.44	0.63	0.80	0.46	0.84	1.15	1.45	1.72
R (ph-ph) (Ohms)				45.8	15.3	8.5	5.72	19.4	6.2	3.16	2.31	1.71
L (ph-ph) (mH)				98.8	43.4	27.9	20.2	59.2	25.8	16.0	12.6	10.1
Rated Speed 3000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 0.93 K_e (V/krpm) = 57.00								
Rated Torque (Nm)	0.60	1.20	1.80	1.1	2.0	2.8	3.5	2.0	3.9	5.4	6.8	8.1
Stall Current (A)	0.98	1.68	2.46	1.3	2.4	3.4	4.2	2.5	4.7	6.4	8.1	9.7
Rated Power (kW)	0.21	0.43	0.64	0.35	0.63	0.88	1.10	0.63	1.23	1.70	2.14	2.54
R (ph-ph) (Ohms)	30.0	14.7	9.6	18.9	6.26	3.50	2.38	8.03	2.68	1.57	1.03	0.77
L (ph-ph) (mH)	67.3	43.0	30.9	42.5	18.4	11.9	8.82	25.6	12.0	7.91	5.60	4.65
Rated Speed 4000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 0.72 K_e (V/krpm) = 44.00								
Rated Torque (Nm)	C/D	C/D	C/D	1.0	1.7	2.3	2.9	1.8	3.0	4.0	4.9	5.7
Stall Current (A)				1.7	3.1	4.4	5.5	3.2	6.0	8.2	10.5	12.5
Rated Power (kW)				0.42	0.71	0.96	1.21	0.75	1.26	1.68	2.05	2.39
R (ph-ph) (Ohms)				10.2	3.39	1.92	1.48	5.15	1.64	0.92	0.62	0.43
L (ph-ph) (mH)				24.6	10.8	7.14	5.42	15.5	6.77	4.61	3.46	2.54
Rated Speed 6000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 0.47 K_e (V/krpm) = 28.50								
Rated Torque (Nm)	0.48	0.91	1.35	0.9	1.6	2.1	2.6	1.3	2.1	2.8	C/D	C/D
Stall Current (A)	1.66	3.33	4.80	2.6	4.7	6.6	8.3	4.9	9.2	12.6		
Rated Power (kW)	0.33	0.63	0.99	0.57	1.01	1.32	1.63	0.82	1.32	1.76		
R (ph-ph) (Ohms)	9.6	3.8	2.5	4.5	1.49	0.95	0.65	2.01	0.67	0.35		
L (ph-ph) (mH)	21.5	11.1	8.1	10.7	4.73	3.10	2.33	6.41	3.01	1.77		

For 3 Phase VPWM Drives 200-240Vrms

Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency.
All other figures relate to a 20°C motor temperature.
Maximum intermittent winding temperature is 140°C.

115E2					142E2					190E2							
A	B	C	D	E	A	B	C	D	E	A	B	C	D	E	F	G	H
3.5	6.6	9.4	12.4	15.3	5.7	10.8	15.3	19.8	23.4	C/D	21.8	C/D	41.1	C/D	58.7	C/D	73.2
10.5	19.8	28.2	37.2	45.9	17.1	32.4	45.9	59.4	70.2		65.4		123.0		176.0		219.0
14	26.4	37.6	49.6	61.2	22.8	43.2	61.2	79.2	93.6	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
4.4	6.7	9.0	11.4	13.8	9.0	15.6	22.2	28.8	35.4		48.7		86.4		123.1		161.8
9.5	11.8	14.1	16.6	18.9	23.3	29.9	36.5	43.1	49.7		93.9		131.6		168.3		207.0
175	185	198	217	241	213	217	275	301	365		240		242		319		632
0.06	0.10	0.14	0.18	0.21	0.09	0.16	0.23	0.30	0.35		0.30		0.54		0.72		0.99
7.80	9.70	11.60	13.50	15.40	10.00	13.30	16.10	18.90	21.70		25.30		33.90		42.50		51.30
9.00	10.90	12.80	14.70	17.20	12.20	15.00	17.80	19.60	23.40		27.30		35.90		44.50		53.10
3.2	6.1	8.7	10.8	14.0	5.3	10.3	14.6	18.4	21.3	C/D	20.0	C/D	36.9	C/D	50.4	C/D	C/D
2.5	4.8	6.8	8.9	11.0	4.1	7.8	11.0	14.2	16.8		15.6		29.4		42.0		
0.67	1.28	1.82	2.26	2.93	1.11	2.16	3.06	3.85	4.46		4.19		7.73		10.6		
9.09	2.82	1.51	0.99	0.82	4.28	1.33	0.75	0.45	0.32		0.50		0.15		0.10		
47.3	20.6	13.1	9.54	7.86	33.7	15.1	10.3	6.96	5.58		7.98		3.32		2.73		
3.0	5.5	8.1	10.4	12.6	4.9	9.0	12.2	15.8	N/A	C/D	19.2	C/D	33.0	C/D	C/D	C/D	N/A
3.8	7.1	10.2	13.4	16.5	6.2	11.7	16.5	21.3			23.5		44.2				
0.94	1.73	2.54	3.27	3.96	1.54	2.83	3.83	4.96			6.03		10.4				
4.01	1.30	0.73	0.47	0.37	1.90	0.59	0.31	0.20			0.25		0.08				
20.1	9.16	6.07	4.26	3.49	15.0	6.85	4.20	1.94			3.98		1.87				
2.5	4.7	6.3	7.5	C/D	3.6	7.0	C/D	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
4.9	9.2	13.1	17.3		8.0	15.0											
1.05	1.97	2.64	3.14		1.51	2.93											
2.62	0.82	0.44	0.29		1.20	0.36											
12.6	5.48	3.57	2.53		9.45	4.08											
2.2	4.0	C/D	N/A	N/A	2.9	C/D	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
7.5	14.1				12.2												
1.38	2.51				1.82												
0.96	0.30				0.49												
4.80	2.09				3.96												

Unimotor Servo motor for 3 Phase VPWM Drives 380-480Vrms

$\Delta t = 100^\circ\text{C}$ winding 40°C maximum ambient

All data subject to +/-10% tolerance

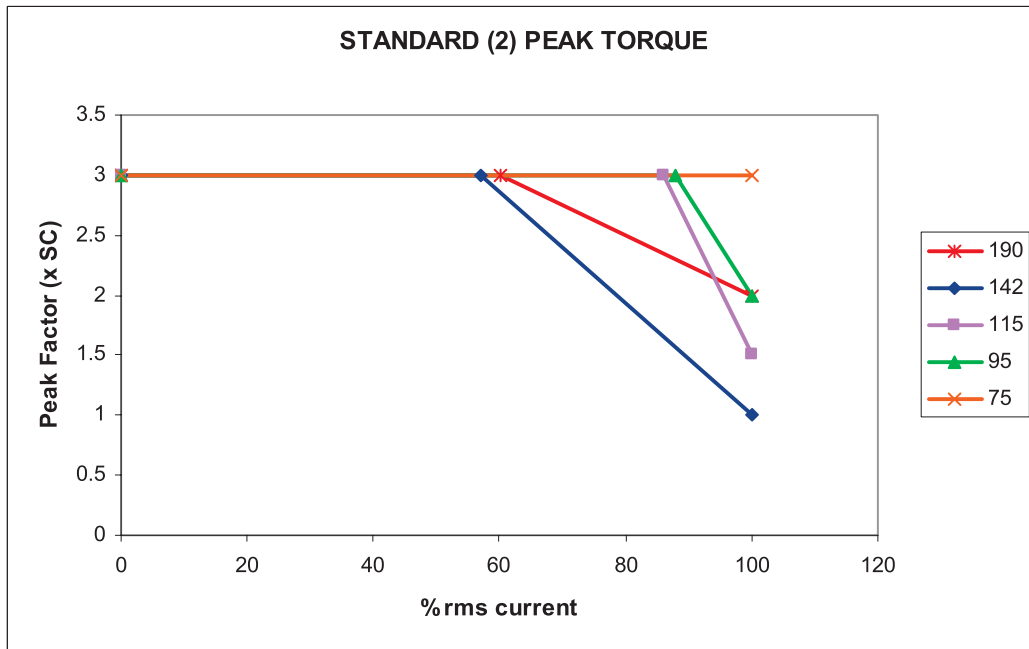
Motor Frame Size (mm)	055U2			075U2				095U2				
Frame Length	A	B	C	A	B	C	D	A	B	C	D	E
Continuous Stall Torque (Nm)	0.72	1.40	2.11	1.2	2.2	3.1	3.9	2.3	4.3	5.9	7.5	9.0
Standard (2) Peak Torque selection max (Nm)	2.75	5.50	8.25	3.6	6.6	9.3	11.7	6.9	12.9	17.7	22.5	27.0
High (P) Peak Torque selection max (Nm)	N/A	N/A	N/A	6	11	15.5	19.5	10.4	19.4	26.6	33.8	40.5
Standard Inertia (kgcm ²)	0.12	0.23	0.34	0.7	1.2	1.6	2.0	1.8	2.9	4.0	5.1	6.2
High Inertia (kgcm ²)				1.1	1.5	2.0	2.4	3.7	4.8	5.9	7.0	8.1
Winding Thermal Time Const. (sec)				81	74	94	100	172	168	183	221	228
Maximum Cogging (Nm)	0.03	0.05	0.07	0.02	0.03	0.04	0.05	0.03	0.06	0.08	0.10	0.13
Standard motor weight unbraked (kg)	1.20	1.50	1.80	3.60	4.40	5.20	6.00	5.10	6.30	7.50	8.70	9.90
Standard motor weight braked (kg)	1.60	1.90	2.20	4.10	4.90	5.70	6.50	5.70	6.90	8.70	9.30	10.50
Rated Speed 2000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 2.40 K_e (V/krpm) = 147.00								
Rated Torque (Nm)	C/D	C/D	C/D	1.1	2.1	3.0	3.8	2.2	4.0	5.5	6.9	8.2
Stall Current (A)				0.5	1.0	1.3	1.7	1.0	1.8	2.5	3.2	3.8
Rated Power(kW)				0.23	0.44	0.63	0.80	0.46	0.84	1.15	1.45	1.72
R (ph-ph) (Ohms)				144	48.2	25.0	15.7	59.0	17.0	9.90	6.00	4.30
L (ph-ph) (mH)				214	99.2	59.2	44.7	131	54.5	36.5	25.6	18.9
Rated Speed 3000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 1.60 K_e (V/krpm) = 98.00								
Rated Torque (Nm)	0.60	1.20	1.80	1.1	2.0	2.8	3.5	2.0	3.9	5.4	6.8	8.1
Stall Current (A)	0.98	0.95	1.34	0.8	1.4	2.0	2.5	1.5	2.7	3.7	4.7	5.7
Rated Power(kW)	0.21	0.43	0.64	0.35	0.63	0.88	1.10	0.63	1.23	1.70	2.14	2.54
R (ph-ph) (Ohms)	30.0	46.0	32.0	60.8	20.1	10.5	7.5	24.5	6.80	4.00	2.50	2.00
L (ph-ph) (mH)	67.3	132.3	103.0	98.4	41.8	27.6	19.7	57.9	24.3	15.5	10.9	8.50
Rated Speed 4000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 1.20 K_e (V/krpm) = 73.50								
Rated Torque (Nm)	C/D	C/D	C/D	1.0	1.7	2.3	2.9	1.8	3.0	4.0	4.9	5.7
Stall Current (A)				1.0	1.9	2.6	3.3	2.0	3.6	5.0	6.3	7.5
Rated Power(kW)				0.42	0.71	0.96	1.21	0.75	1.26	1.68	2.05	2.39
R (ph-ph) (Ohms)				36.8	10.5	6.30	4.20	12.7	4.08	2.10	1.50	1.03
L (ph-ph) (mH)				54.9	24.8	14.9	10.8	31.5	13.6	8.50	6.30	4.80
Rated Speed 6000 (rpm)	K_t (Nm/A) = K_e (V/krpm) =			K_t (Nm/A) = 0.80 K_e (V/krpm) = 49.00								
Rated Torque (Nm)	0.48	0.91	1.35	0.9	1.6	2.1	2.6	1.3	2.1	2.8	C/D	C/D
Stall Current (A)	0.98	1.91	2.68	1.5	2.8	3.9	4.9	2.9	5.4	7.4		
Rated Power(kW)	0.33	0.63	0.99	0.57	1.01	1.32	1.63	0.82	1.32	1.76		
R (ph-ph) (Ohms)	30.0	11.4	8.0	15.0	5.00	2.66	1.90	5.45	1.82	1.05		
L (ph-ph) (mH)	67.3	33.1	25.7	24.0	10.6	6.80	4.80	14.1	6.00	3.80		

Servo motor for 3 Phase VPWM Drives 380-480Vrms

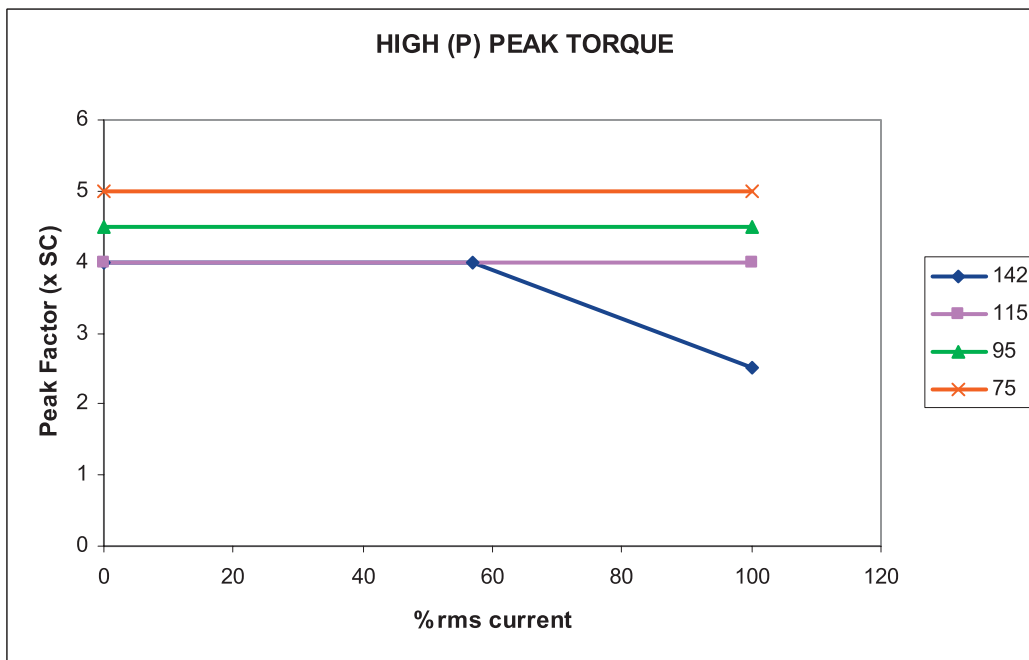
Stall torque, rated torque and power relate to maximum continuous operation tested in a 20°C ambient at 12kHz drive switching frequency.
 All other figures relate to a 20°C motor temperature.
 Maximum intermittent winding temperature is 140°C.

115U2					142U2					190U2							
A	B	C	D	E	A	B	C	D	E	A	B	C	D	E	F	G	H
3.5	6.6	9.4	12.4	15.3	5.7	10.8	15.3	19.8	23.4	9.6	21.8	31.1	41.1	50.6	58.7	66.0	73.2
10.5	19.8	28.2	37.2	45.9	17.1	32.4	45.9	59.4	70.2	28.8	65.4	93.3	123	151.6	176	198.0	219
14	26.4	37.6	49.6	61.2	22.8	43.2	61.2	79.2	93.6	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
4.4	6.7	9.0	11.4	13.8	9.0	15.6	22.2	28.8	35.4	29.9	48.7	67.5	86.4	105.0	123.1	142.9	161.8
9.5	11.8	14.1	16.6	18.9	23.3	29.9	36.5	43.1	49.7	75.1	93.9	112.7	131.6	150.2	168.3	188.1	207
175	185	198	217	241	213	217	275	301	365	217	240	241	242	281	319	476	632
0.06	0.10	0.14	0.18	0.21	0.09	0.16	0.23	0.30	0.35	0.12	0.30	0.40	0.54	0.66	0.72	0.86	0.99
7.80	9.70	11.60	13.50	15.40	10.00	13.30	16.10	18.90	21.70	21.00	25.30	29.60	33.90	38.20	42.50	46.80	51.30
9.00	10.90	12.80	14.70	17.20	12.20	15.00	17.80	19.60	23.40	23.00	27.30	31.60	35.90	40.20	44.50	48.80	53.10
3.2	6.1	8.7	10.8	14.0	5.3	10.3	14.6	18.4	21.3	9.3	20.0	28.4	36.9	43.8	50.4	53.0	54.7
1.5	2.8	4.0	5.2	6.4	2.4	4.5	6.4	8.3	9.8	4.0	9.1	13.0	17.2	21.1	24.5	27.5	30.5
0.67	1.28	1.82	2.26	2.93	1.11	2.16	3.06	3.85	4.46	1.90	4.19	5.90	7.73	9.20	10.6	11.1	11.5
27.8	8.55	4.55	2.96	2.17	12.5	3.60	2.10	1.35	0.98	6.15	1.80	0.83	0.56	0.39	0.33	0.30	0.23
94.6	40.5	25.7	18.6	14.7	58.0	29.8	18.7	13.6	10.7	52.90	28.10	15.00	13.0	8.68	8.90	6.73	6.30
3.0	5.5	8.1	10.4	12.6	4.9	9.0	12.2	15.8	18.0	8.7	19.2	25.0	33.0	34.0	35.0	36.0	36.8
2.2	4.2	5.9	7.8	9.6	3.6	6.8	9.6	12.4	14.7	6.0	13.7	19.4	25.7	31.6	36.7	41.3	45.8
0.94	1.73	2.54	3.27	3.96	1.54	2.83	3.83	4.96	5.65	2.73	6.03	7.85	10.4	10.7	11.0	11.3	11.6
12.6	3.86	2.02	1.40	1.10	5.63	1.72	0.94	0.61	0.44	2.73	0.79	0.41	0.30	0.17	0.14	0.13	0.09
43.1	18.6	11.4	8.60	7.40	31.0	13.3	8.30	6.10	4.80	23.50	13.20	7.35	6.11	3.86	3.60	2.99	2.46
2.5	4.7	6.3	7.5	8.7	3.6	7.0	8.9	10.7	12.2	C/D	C/D	C/D	C/D	N/A	N/A	N/A	N/A
3.0	5.5	7.9	10.4	12.8	4.8	9.0	12.8	16.5	19.5								
1.05	1.97	2.64	3.14	3.64	1.51	2.93	3.73	4.48	5.11								
6.91	2.14	1.16	0.73	0.57	3.12	1.00	0.53	0.35	0.24								
23.5	10.2	6.60	4.70	3.90	17.6	7.50	4.70	3.60	2.70								
2.2	4.0	C/D	C/D	N/A	2.9	4.5	C/D	C/D	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
4.4	8.3				7.2	13.5											
1.38	2.51				1.82	2.83											
3.10	0.97				1.42	0.46											
15.5	4.81				7.72	3.44											

Peak Torque Information



Peak Torque defined for a maximum period of 250 ms, RMS 3000 rpm, $\Delta T_{max} = 100^{\circ}C$, $40^{\circ}C$ ambient.
SC = Stall Current



Peak Torque defined for a maximum period of 250 ms, RMS 3000 rpm, $\Delta T_{max} = 100^{\circ}C$, $40^{\circ}C$ ambient.
SC = Stall Current

Motor Specification

Low Voltage Directive 2006/95/EC

Note: Machinery Directive 89/392/EEC amended to 98/37/EC Low Voltage Directive 73/23/EEC superseded by directive 2006/95/EC on 16/01/07, which specifically excludes electric motors.

EN 60034		General requirements for rotating electrical machinery
EN 60034-1	Duty: S1 Continuous Storage: -15°C to +40°C Operating: Min ambient 0°C; max ambient 40°C Less than 1000M altitude Relative humidity: 90% non condensing	
EN 60034-5	Degree of Ingress protection: IP65 (when mounted and connected)	
EN 60034-6	Method of cooling: free circulation, free convection	
EN 60034-7	Flange mounted: horizontally or vertically	
EN 60034-8	Terminal markings: U V W,	
EN 60034-11	Thermal protection: PTC thermistor, 145°C on 075-190 motors Thermal protection: PTC thermistor, 150°C on 055 motors	
EN 60034-18	Insulation system: Class F 600V, UL number E214439 on 075-190 motors Insulation system: Class F 600V, on 055 motors	
EN 60034-25	The design and performance of motors specifically designed for converter supply	
EN 60072		Dimensions and output for rotating electrical machines
EN 60072-1	Type N (Customer variants)	
ISO1940-1	Balancing: to G6.3, (ISO8821 half key convention)	

Standard equipment is not deemed suitable for use in an explosive atmosphere.

This product has been designed to be operated with Control Techniques Servo drives and must not be put into service unless the machinery into which it is to be incorporated has been declared in conformity with the provisions of the machinery directive.

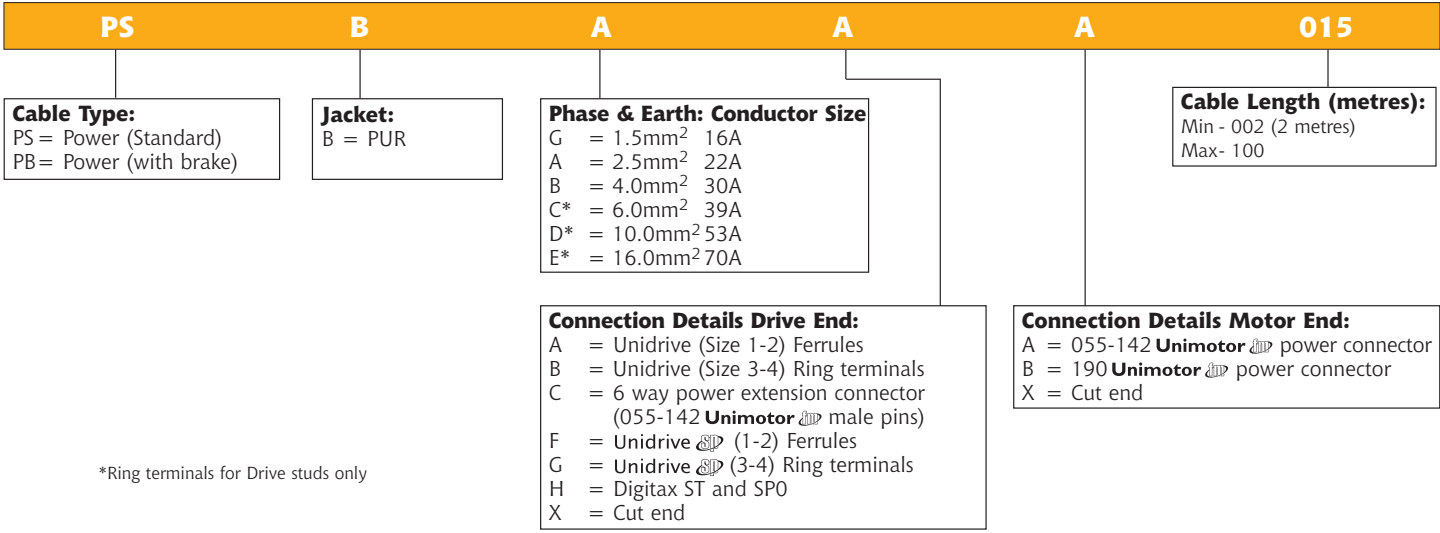
Standard Brake Specification

Motor Frame	Supply Volts	Input Power	Static Torque		Release Time	Moment of Inertia	Backlash
			Standard brake (01)	High energy brake (05)			
Size	VDC	Watts	Nm	Nm	ms nom	kgcm ² *	Degrees**
055	24	6.3	1.8	N/A	22	0.03	0.75
075	24	6.3	2	2.2	22	0.07	1.03
095	24	16	11	12.2	60	0.39	0.94
115	24	16	11	12.2	60	0.44	0.56
142	24	19.5	18	22	75	0.54	0.56
190(A-D)	24	25	38	42	95	3.07	0.77
190(E-H)	24	25	60	67	120	4.95	0.77

*Note 1 kgcm² = 1x10⁻⁴kgm² **Backlash figure will increase with time

- The brakes are intended for parking duty and are not for dynamic or safety use.
- The brake will engage when power is removed.
- Refer to your Drive Centre or Distributor if your application requires dynamic braking in emergency conditions.
- To provide protection to the brake control circuit it is recommended that a diode is connected across the output terminals of the solid state or relay contacts devices.
- Larger torque brakes are available as an option. Please contact your Drive Centre or Distributor for details.
- Figures are shown at 20°C brake temperature. Apply the de rate factor of 0.7 to the standard brake torque figures if motor temperature is above 100°C. The de rate factor does not apply to the High energy brake.

Cable Information



Cable type - PS for motor without brakes, PB for motors with brake.

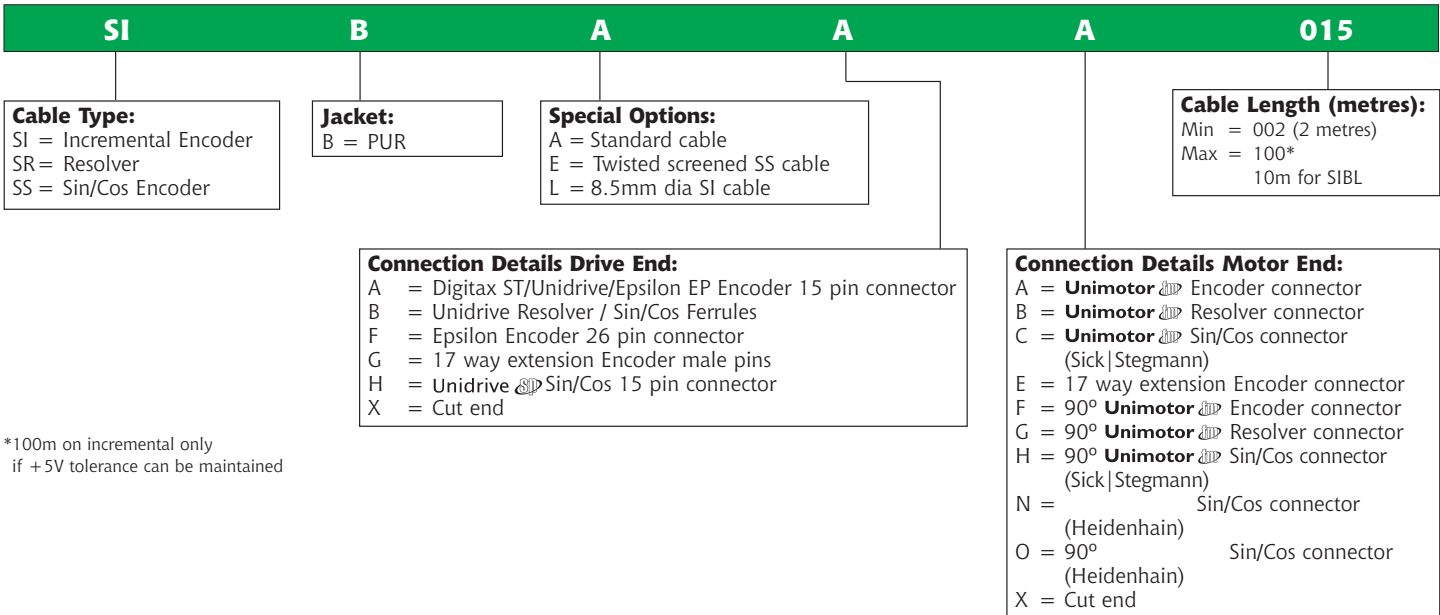
Jacket - B is for a PUR sheath and is the standard selection.

Conductor size - Select the conductor size according to the motors STALL CURRENT.
 Cables of 6mm² and above will be fitted with ring terminals only.
 Ratings are for individual cables (not lashed together) in free air temperature up to 40°C - make allowances as appropriate.

Connection detail drive end - Select the correct drive end connection for the drive in use.

Connection detail motor end - Select the correct motor end connection for the motor in use.

Length - Numbers represent the required cable length in metres.



Cable type - Choose the cable type to match the feedback device.

Jacket - B is for a PUR sheath and is the standard selection.

Special options - A is for standard cable. L is for the low cost 8.5mm incremental cable.

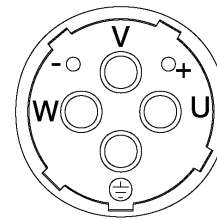
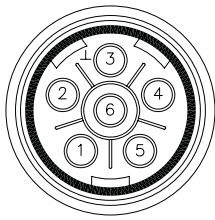
Connection detail drive end - Select the correct drive end connection for the drive in use.

Connection detail motor end - Select the correct motor end connection for the motor feedback device in use.

Length - Numbers represent the required cable length in metres.

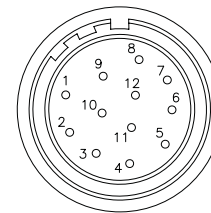
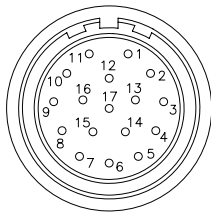
Motor connector details

Power Plug



Pin	055-142 with brake	055-142 without brake	Pin	190 with brake	190 without brake
1	Phase U (R)	Phase U (R)	U	Phase U (R)	Phase U (R)
2	Phase V (S)	Phase V (S)	V	Phase V (S)	Phase V (S)
3	Earth	Earth	⊕	Earth	Earth
4	Phase W (T)	Phase W (T)	W	Phase W (T)	Phase W (T)
5	Brake		+	Brake	
6	Brake		-	Brake	
Shell	Screen	Screen	Shell	Screen	Screen

Signal Plugs



Pin	Incremental Encoder (KP, MP, CP, CA, MA)	Heidenhain Sin/Cos Encoders (EM, FM, EC, FC, EB, FB)	Resolver (AE, AR)	Sick Stegmann Sin/Cos Encoders (TL, UL, RB, SB)
1	Thermistor	Thermistor	Excitation high	REF Cos
2	Thermistor	Thermistor	Excitation low	+ Daten
3		Screen (Optical encoder only)	Cos high	- Daten
4	S1		Cos low	+ Cos
5	S1 Inverse		Sin high	+ Sin
6	S2		Sin low	REF Sin
7	S2 Inverse		Thermistor	Thermistor
8	S3	+ Clock	Thermistor	Thermistor
9	S3 Inverse	- Clock		Screen
10	Channel A	+ Cos		0 Volts
11	Index	+ Data		-
12	Index Inverse	- Data		+ Volts
13	Channel A Inverse	- Cos		
14	Channel B	+ Sin		
15	Channel B Inverse	- Sin		
16	+ 5V	+ 8V		
17	0 Volts	0 Volts		
Body	Screen	Screen		Screen

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